

ADVICE. Take advantage of the TA’s problem sessions. This is the **principal venue to discuss past homework and test problems**. Note that such problems may prop up in future tests.

READING. Review all previous handouts and readings. New reading, due Tuesday, Feb 28: text 8.1 (polynomial time reductions)

New reading, due Tuesday, March 7: text 6.3 (Segmented Least Squares (dynamic programming)); text pp.83–94 (depth-first search (DFS)); 3.6 topological ordering pp.99–104.

HOMEWORK. Please **print your name on each sheet**. Put each solution on a separate sheet. Please try to make your solutions easily readable.

This homework is due on **Tuesday, February 28**.

- 9.1 (10 points) Suppose we have a black box that takes as input a pair (G, k) where G is an undirected graph and k is an integer, and outputs “YES” if G has a clique (complete subgraph) with k vertices. Given an undirected graph H , use this black box to find a largest clique in H in polynomial time, including a polynomial number of queries to the black box. *Hint.* First find the size of the largest clique; then, if this size is k , find a clique of size k .

For the next sequence of problems, we need the concept of *Karp-reductions* between languages.

Definition. Let $L_1 \subseteq \Sigma_1^*$ and $L_2 \subseteq \Sigma_2^*$ be languages. We say that a function $f : \Sigma_1^* \rightarrow \Sigma_2^*$ is a **Karp-reduction** from L_1 to L_2 if

- (i) f is polynomial-time computable;
- (ii) $(\forall x \in \Sigma_1^*)(x \in L_1 \Leftrightarrow f(x) \in L_2)$.

We say that L_1 is **Karp-reducible** to L_2 (denoted by $L_1 <_K L_2$) if there exists a Karp-reduction from L_1 to L_2 .

- 9.2 (10 points) Prove: if $L_2 \in P$ and $L_1 <_K L_2$ then $L_1 \in P$. Here P is the class of languages recognizable in polynomial time; recognizing a language means solving the membership problem for the language, i. e., deciding, for input $x \in \Sigma^*$, whether or not $x \in L$. Be specific about the exponents involved: if L_2 can be recognized in $O(n^a)$ and the function f can be computed in $O(n^b)$ then what is the smallest exponent c you can guarantee so that L_1 is recognizable in $O(n^c)$ where for each computation, n refers to the length of the input of that computation.

- 9.3 A linear inequality in the variables x, y, z is an inequality of the form $3x - 5y + z \leq 6$. (We may replace the coefficients 3, -5 , 1, 6 by arbitrary real numbers, and the number of variables may also be arbitrary. We

shall assume, however, that *all coefficients are integers*.) A linear program (LP) is a set of linear inequalities with integer coefficients (including the right hand side). A LP is *feasible* if it has a solution (an assignment of real numbers to the variables satisfying all inequalities).

Let LPf (*linear program feasibility*) denote the set of feasible LPs. Let ILPf (*integer linear program feasibility*) denote the set of those LPs which have an integer solution (all unknowns take integer values). Let $(0,1)$ -ILPf denote the set of those LPs which have a $(0,1)$ -solution (each unknown takes the value zero or one).

- (i) (2 points) Give an example of a LP which is feasible (has solution(s) in real numbers) but which is not feasible as an ILP (has no integer solutions). Use as few variables as possible.
- (ii) (4 points) Same as item (i) but all coefficients in the LP must be 0, 1, or -1 , including the numbers on the right hand side. (A correct solution to this question also earns you the 2 points for part (i).)
- (iii) (10 points) Let 3-COL denote the set (language) of 3-colorable graphs. Prove: $3\text{-COL} <_K (0,1)\text{-ILPf}$.