

1. Let $R(t) = \langle 1, 1, 1 \rangle + t\langle -1, -1, -1 \rangle$ and let S be the unit sphere at the origin. For what values of t does $R(t)$ intersect S ?
2. An *axis-aligned bounding box* (AABB) in 2D is defined by four scalar values:

$$\langle \min X, \max X, \min Y, \max Y \rangle$$

We use $\langle 1, -1, 1, -1 \rangle$ to denote the empty AABB. Let

$$bb_1 = \langle \min X_1, \max X_1, \min Y_1, \max Y_1 \rangle$$

and

$$bb_2 = \langle \min X_2, \max X_2, \min Y_2, \max Y_2 \rangle$$

be two *non-empty* AABBs.

- (a) What is the minimum AABB that contains the union of bb_1 and bb_2 ?
 - (b) What is the minimum AABB that contains the intersection of bb_1 and bb_2 ?
 - (c) What is the minimum AABB that contains the difference of bb_1 and bb_2 (i.e., $bb_1 \setminus bb_2$)?
3. Let $\mathbf{M} = \begin{bmatrix} & \mathbf{N} & \\ 0 & 0 & 0 & 1 \end{bmatrix}$ be a 4×4 matrix. Show that $\mathbf{M}\langle x, y, z, 1 \rangle^T$ is the same as $\mathbf{M}\langle hx, hy, hz, h \rangle^T$ after homogenization.
 4. Suppose you have an application with a near plane of 10 meters, a far plane of 100 kilometers (10^5 meters), and a minimum feature size of 1 meter. How many bits of Z-buffer do you need to avoid Z-fighting? What if the near plane is at 1 meter?